

## WE CLAIM:

1           1. A method of machining a hollow metal workpiece  
2   having a plurality of small-diameter throughgoing holes and at  
3   least one large-diameter hole, the method comprising the steps  
4   of:

5           picking up from a transfer station by a grab a hollow  
6   workpiece and displacing the workpiece from the transfer station  
7   to a machining station;

8           thereafter, while holding the workpiece in the grab,

9           a) engaging a tool from outside with a first  
10           exterior surface of the workpiece and thereby  
11           finishing the first exterior surface;

12           b) reorienting the workpiece by the grab and  
13           engaging a tool with a second exterior  
14           surface of the workpiece offset from the  
15           first exterior surface and thereby finishing  
16           the second exterior surface;

17           c) fitting another tool through the large-diameter  
18           hole of the workpiece and positioning the  
19           other tool inside the workpiece adjacent one  
20           of the small-diameter holes;

21           d) coupling a drive spindle through the one small-  
22           diameter hole of the workpiece with the other  
23           tool and machining an inner surface of the

24                   workpiece adjacent the one small-diameter  
25                   hole with the other tool; and  
26                   e) repeating steps b), c), and d) to finish  
27                   another interior surface of the workpiece  
28                   adjacent another of the small-diameter holes;  
29                   and  
30                   displacing the workpiece from the machining station  
31                   back to the transfer station and releasing it from the grab.

1                   2. The machining method defined in claim 1 wherein the  
2                   exterior surfaces are surfaces of the small-diameter holes.

1                   3. The machining method defined in claim 2 wherein the  
2                   surfaces of the small-diameter holes are generally cylindrical.

1                   4. The machining method defined in claim 1 wherein in  
2                   step b) the workpiece is rotated about an axis through about 90°.

1                   5. The machining method defined in claim 1, further  
2                   comprising the step during step d) of

3           engaging a tailstock through another of the small-  
4   diameter holes with the other tool after coupling of the other  
5   tool to the drive spindle to brace the other tool.

1           6. An apparatus for machining a hollow metal workpiece  
2   having a plurality of small-diameter throughgoing holes and at  
3   least one large-diameter hole to produce a part having a  
4   plurality of finished exterior and interior surfaces, the  
5   apparatus comprising:

6           means including a grab for picking up from a transfer  
7   station the hollow workpiece and displacing the workpiece from  
8   the transfer station to a machining station;

9           means including a tool engageable with a first exterior  
10   surface of the workpiece in the grab for finishing the first  
11   exterior surface;

12          drive means connected to the grab and for reorienting  
13   the workpiece and engaging the tool with a second exterior  
14   surface of the workpiece offset from the first exterior surface  
15   and thereby finishing the second exterior surface;

16          means including for fitting another tool through the  
17   large-diameter hole of the workpiece and positioning the other  
18   tool inside the workpiece adjacent one of the small-diameter  
19   holes;

20          means including a drive spindle engageable through the  
21   one small-diameter hole of the workpiece for coupling the spindle

22 to the other tool and machining an inner surface of the workpiece  
23 adjacent the one small-diameter hole with the other tool; and  
24 means for displacing the workpiece from the machining  
25 station back to the transfer station and releasing it from the  
26 grab.

1 7. The machining apparatus defined in claim 6, further  
2 comprising

3 a tailstock engageable through another of the small-  
4 diameter holes with the other tool after coupling of the other  
5 tool to the drive spindle to brace the other tool.

1 8. The machining apparatus defined in claim 7 wherein  
2 the tailstock is displaceable parallel to a rotation axis of the  
3 spindle.

1 9. The machining apparatus defined in claim 6 wherein  
2 the tools are all rotatable about parallel axes, the means  
3 including the grab further including:

4 a main slide displaceable perpendicular to the rotation  
5 axes; and

6 a carriage displaceable on the main slide parallel to  
7 the rotation axes and carrying the grab.